Stability in Random Coalition Formation

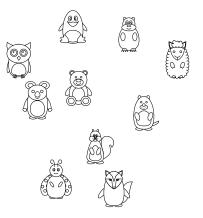
Games, Mechanisms and Social Networks seminar, Warsaw

Sonja Kraiczy

Joint work with Martin Bullinger



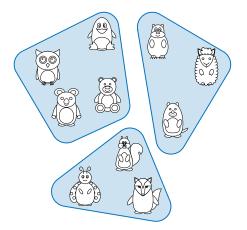
Coalition Formation



Drèze and Greenberg (ECMA 1980)

Sonja Kraiczy

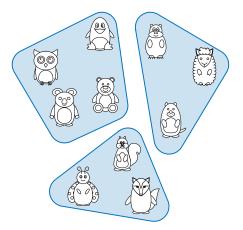
Coalition Formation



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Coalition Formation



How to obtain desirable coalition structures algorithmically?

Drèze and Greenberg (ECMA 1980)

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Random Coalition Formation

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Applications

Team allocation

Cooperative game theory

Clustering

Machine learning

Community detection

Social sciences

Hedonic Games: Formal Model

- Set *N* of *n* agents
- Agent $i \in N$ expresses preference order over coalitions
- Output: coalition structure (= partition) of agents
- **Representation issues:** 2^{n-1} possible coalitions

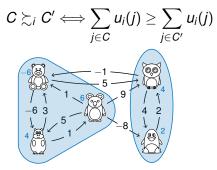


Drèze and Greenberg (ECMA 1980)

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Additively Separable Hedonic Games

- Preferences encoded by utility functions $u_i: N \to \mathbb{Q}$
- Induces hedonic game where

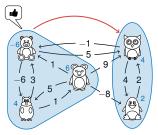


Bogomolnaia and Jackson (GEB, 2002)

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Single-Deviation Stability

Stable partition $\hat{=}$ no beneficial deviation by single agent



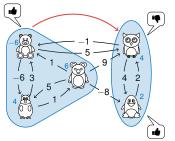
- Nash deviation: beneficial deviation to other coalition
- Nash-stable: there are no Nash deviations

Drèze and Greenberg (ECMA 1980), Dimitrov and Sung (JME 2007)

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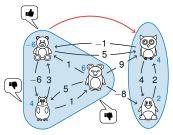


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- Individually stable: every Nash deviation blocked by agent in joined coalition

Drèze and Greenberg (ECMA 1980), Dimitrov and Sung (JME 2007)

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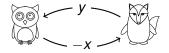
- Nash deviation: beneficial deviation to other coalition
- Nash-stable: there are no Nash deviations
- Individually stable: every Nash deviation blocked by agent in joined coalition
- Contractually Nash-stable: every Nash deviation blocked by agent in abandoned coalition

Drèze and Greenberg (ECMA 1980), Dimitrov and Sung (JME 2007)

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The Run and Chase Instance

- Consider a hedonic game where N = {Owl, Fox}
- Owl prefers to be alone over the grand coalition
- Fox prefers the grand coalition over being alone
- Nash-stability too demanding? Unreasonable?



Complexity of Stability

Theorem

It is NP-complete to decide if there exists a

- Nash-stable partition (Sung and Dimitrov, EJOR 2010),
- individually stable partition (Sung and Dimitrov, EJOR 2010),
- contractually Nash-stable partition (Bullinger, MFCS 2022)

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- Nash-stable partition (Sung and Dimitrov, EJOR 2010),
- individually stable partition (Sung and Dimitrov, EJOR 2010),
- contractually Nash-stable partition (Bullinger, MFCS 2022)
- Hardness for Nash-stability even if utilities restricted to $\{-x, y\}$ for $x \ge y \ge 0$ (Brandt et al., AAAI 2022)
- Reduced instances seem to be artificial corner cases

Existence of Stable Outcomes

- Nash-stable partitions exist for symmetric utilities (Bogomolnaia and Jackson, GEB 2002)
 - PLS-complete to compute (Gairing and Savani, MOR 2019)

Existence of Stable Outcomes

- Nash-stable partitions exist for symmetric utilities (Bogomolnaia and Jackson, GEB 2002)
 - PLS-complete to compute (Gairing and Savani, MOR 2019)
- Individually stable and contractually Nash-stable partitions exist for {-x, y}-utilities (Brandt et al., AAAI 2022)
 - Natural dynamics runs in polynomial time

Stability in Random Games

Question: Do stable coalition structures *typically* exist for many agents?

- Random hedonic game $H(n, \mathcal{D})$
 - Set of n agents
 - Pairwise utility sampled i.i.d. from a distribution \mathcal{D}
- Investigate probability of property \mathfrak{P} (e.g., stability) when *n* tends to infinity:

$$\lim_{n\to\infty} \mathbb{P}(\mathcal{H}(n,\mathcal{D}) \text{ satisfies } \mathfrak{P}) = ?$$

First Observations

Grand coalition (all agents in one large coalition)

- Nash-stable if \mathcal{D} has positive mean, e.g., $\mathcal{D} = U(-1, 2)$,
- contractually Nash-stable if positive weight on positive utility,
- not individually stable if \mathcal{D} has mean 0, e.g., $\mathcal{D} = U(-1, 1)$

Theorem (Bullinger and Kraiczy, 2024)

Let $\mathcal{D} = U(-1, 1)$. Then, $\lim_{n\to\infty} \mathbb{P}(H(n, \mathcal{D}) \text{ admits Nash-stable partition}) = 0$. Moreover, there exists an efficient algorithm \mathcal{A} such that $\lim_{n\to\infty} \mathbb{P}(\mathcal{A}(H(n, \mathcal{D})) \text{ individually stable}) = 1$, and $\lim_{n\to\infty} \mathbb{P}(\mathcal{A}(H(n, \mathcal{D})) \text{ contractually Nash-stable}) = 1$.

 $H(n, \mathcal{D})$: random hedonic game

Sonja Kraiczy

Exit Denial and Entry Denial

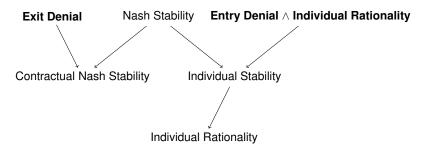
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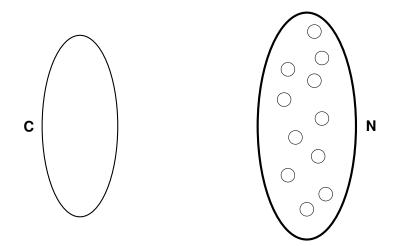


Goal of Algorithm

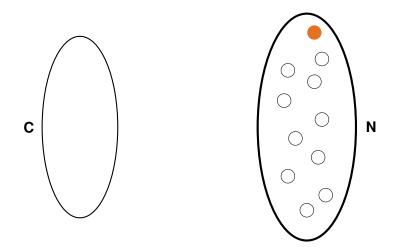
Construct partition that satisfies

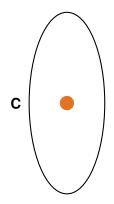
- Individual Rationality
- Entry-Denial
- Exit-Denial

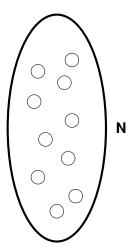
Form coalitions with high mutual utility

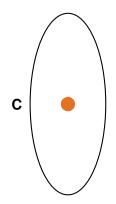


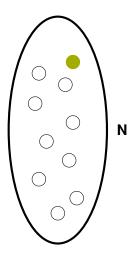
Sonja Kraiczy

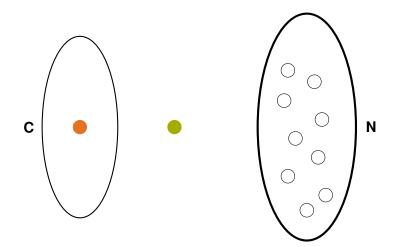


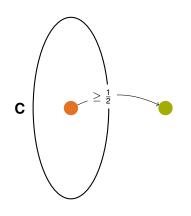


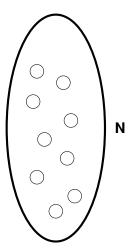


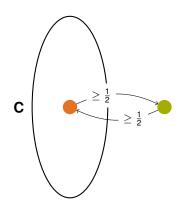


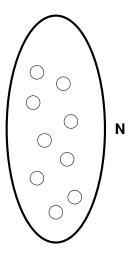


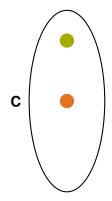


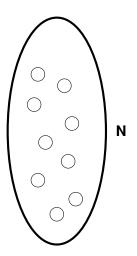


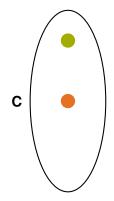


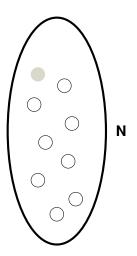


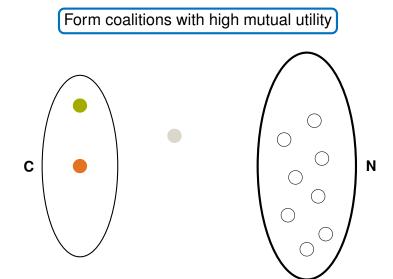


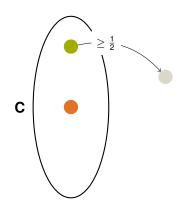


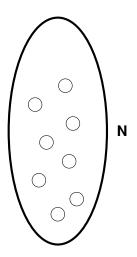


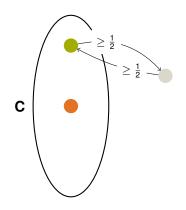


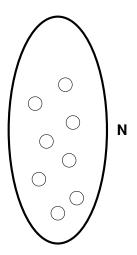


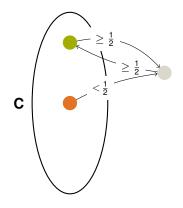


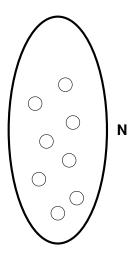


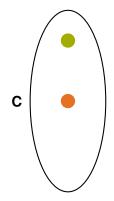


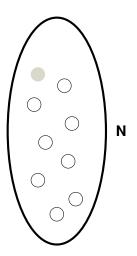


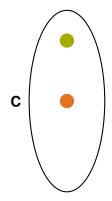


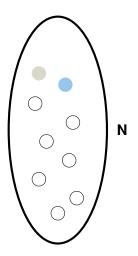


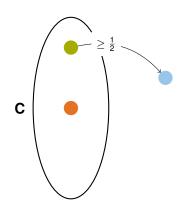


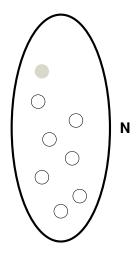


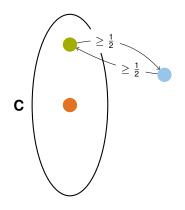


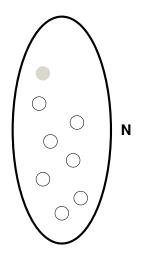


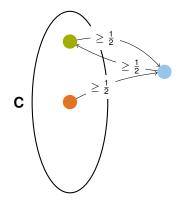


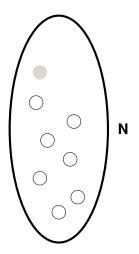


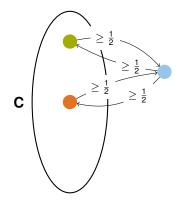


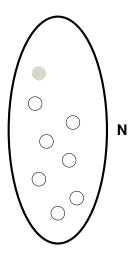


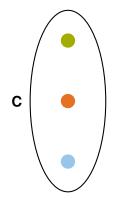


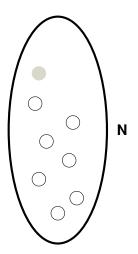












Performance of Stage 1

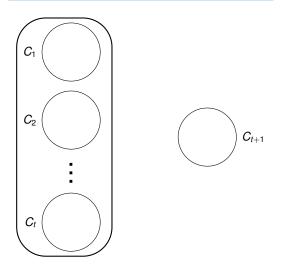
Theorem

With high probability, all except at most $\frac{n}{\log_{16}^2 n}$ agents are assigned to coalitions of size $\left\lceil \frac{\log_{16} n}{2} \right\rceil$.

- Good for individual rationality
- (Nonsingleton) coalitions fail entry denial
- Idea: enlarge coalitions while losing little utility

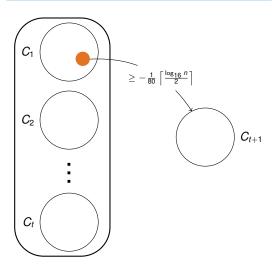
Stage 2: Greedy Clustering

Merge coalitions with small utility loss



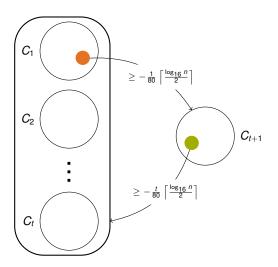
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Performance of Stage 2

Theorem

With high probability, all except at most $20\frac{n}{\log_{16}^2 n} + \alpha \left\lceil \frac{\log_{16} n}{2} \right\rceil$ agents are assigned to coalitions of size $20 \left\lceil \frac{\log_{16} n}{2} \right\rceil$.

- Split agents set into 20 subsets
- Run Stage 1 for each individually
- Merge 20 coalitions each
- Only a finite number of Stage 1 coalitions not merged

Stage 3: Assigning Remainder Agents

Theorem

With high probability, the remainder agents can be added to coalitions for which

- they receive positive utility,
- no utility values revealed in Stage 2.
- First property: individual rationality
- Second property: exit denial

Main Theorem 1

Theorem (Bullinger and Kraiczy, 2024)

Let $\mathcal{D} = U(-1, 1)$. Then, there exists an efficient algorithm \mathcal{A} such that

■ $\lim_{n\to\infty} \mathbb{P}(\mathcal{A}(H(n, D)) \text{ individually stable}) = 1, \text{ and }$

■ $\lim_{n\to\infty} \mathbb{P}(\mathcal{A}(H(n, D)) \text{ contractually Nash-stable}) = 1.$

- Individual rationality: Stages 1 and 3
- Entry denial: Stage 2
- Exit denial: Stages 2 and 3

 $H(n, \mathcal{D})$: random hedonic game

Main Theorem 2

Theorem (Bullinger and Kraiczy, 2024)

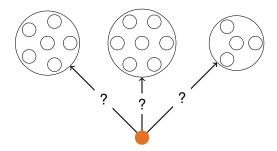
Let $\mathcal{D} = U(-1, 1)$. Then,

 $\lim_{n\to\infty} \mathbb{P}(H(n,\mathcal{D}) \text{ admits Nash-stable partition}) = 0.$

- Sophisticated counting argument
- Bound probability of Nash stability given a fixed number of coalitions
- Multiply with Stirling number of second kind

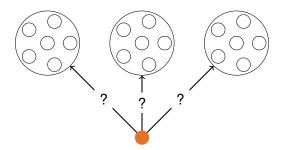
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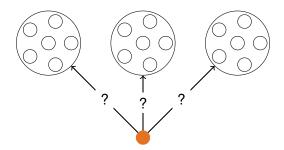
Nash stability captured by comparing sums of i.i.d. random variables

Proof Idea



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- Probability bounded by case of identical-size coalitions

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- Nash stability captured by comparing sums of i.i.d. random variables
- Probability bounded by case of identical-size coalitions
- Challenge: agents are themselves part of a coalition

Conclusion

- Random model of coalition formation
- High probability analysis in large agent limit
- Nash stability fails to exist
- Individual stability and contractual Nash stability derived by efficient algorithm

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Future directions

- Other probability distributions
- Other (stability) concepts
- Other game classes